

# LASERef

Team 18

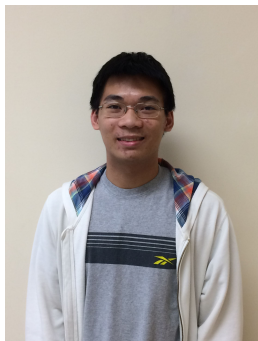
Final Project Review



# Meet the Team



Advisor:  
Professor Tessier



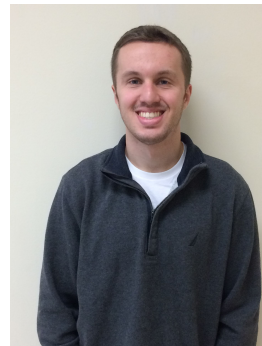
Josh Setow  
EE



Tim Freitas  
EE



Sam Auwerda  
EE



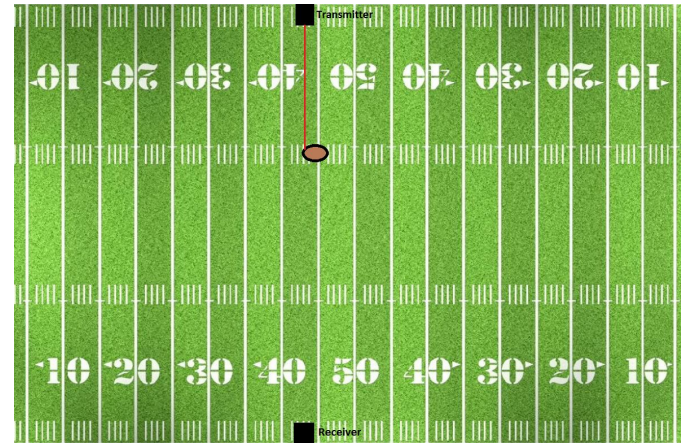
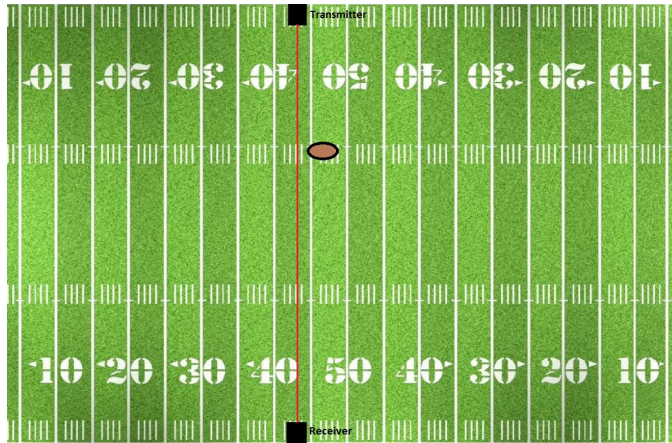
Josh Gallant  
EE

# Overview

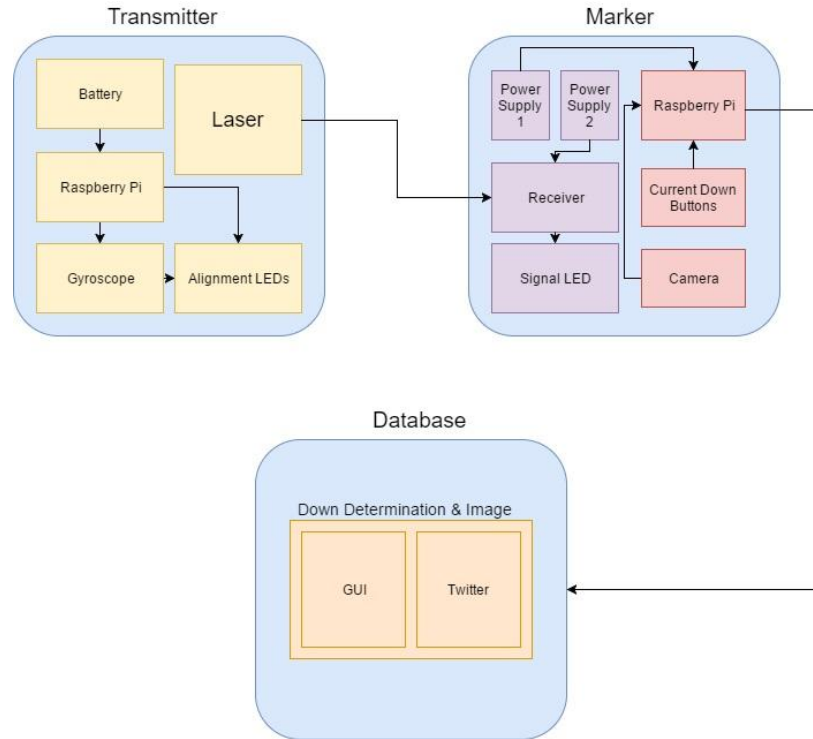
- The current first down marking system slows down gameplay and is prone to human error
  - On close calls the chain crew brings the markers out onto the field to measure
- The LASERef is a break-beam sensor that:
  - Beam a laser across the field to detect if ball has crossed the line
  - Updates a Twitter and GUI with down information and a picture

# Overview

Ball is detected when beam is broken



# Block Diagram



# Promised FPR Deliverables

- New Housing Units for Transmitter and Receiver
  - Padded, Durable, Visually Appealing
- Improved Materials for Light Shield
  - Matte color to avoid unwanted reflection
  - Filter in-front that will allow laser but restrict ambient light
- Improved accuracy on angle detector
- Testing and Data Collection

# Final Receiving Box



# Final Receiving Box



Dimensions:

12" x 5.5" x 13"

Contains:

Receiver Circuit - PCB

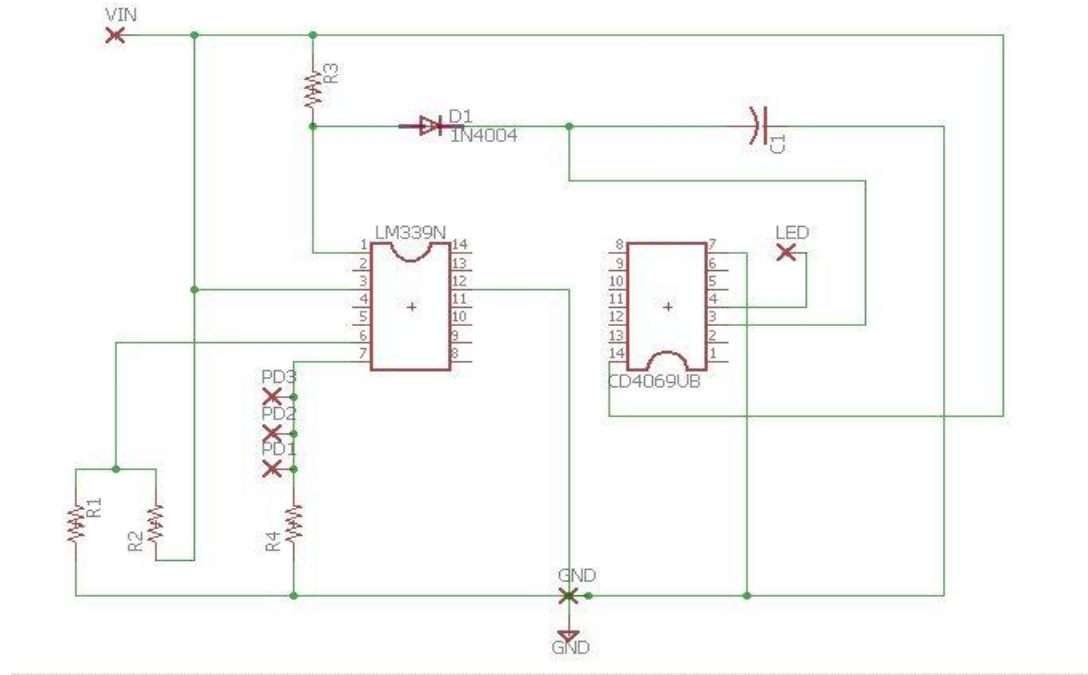
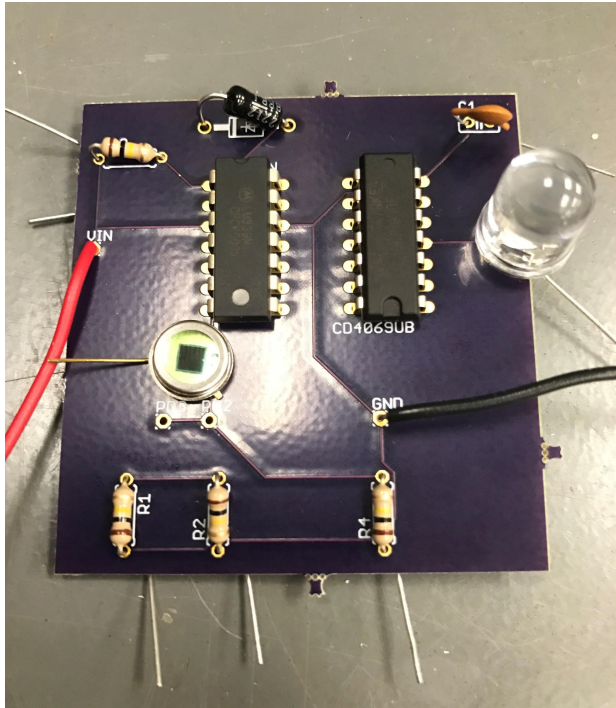
Raspberry Pi

2 Power Sources

Padded



# Printed Circuit Board



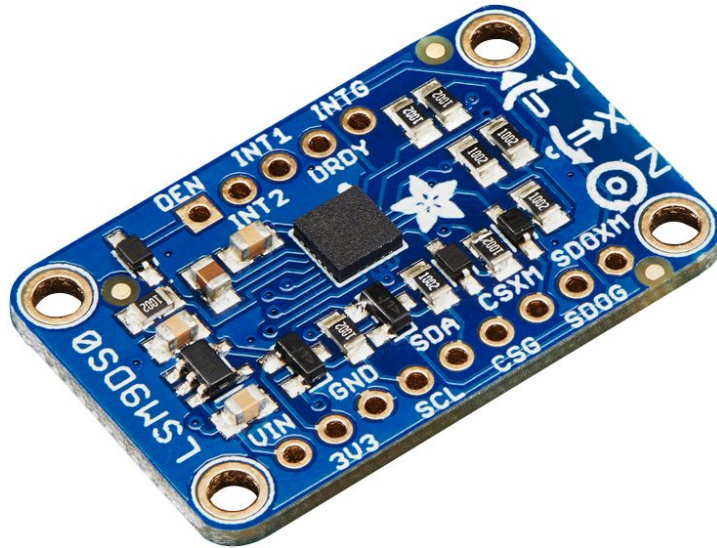
# Transmitter Box

- Built by a 3D printer
- Dimensions:  
5.5" x 7.5" x 7.5"
- Contains:
  - Laser
  - Raspberry Pi
  - Alignment LEDs
  - Gyroscope
  - Power Source



# Angle Detector

- Angle detector is accurate to 1.5 degrees
  - Improvement from 2 degrees



**LASERef**

DOWN Third Down at 04:18:23PM

Update

## Eduroam on the Pi

- Pi now automatically connects to Eduroam
- A monitor no longer needed to set up system
- Equipped with red/green LEDs to show status of Wifi connection



# Final Product Specifications

<b>Specifications</b>	<b>Value</b>
Transmitter Weight	1.96 lbs
Transmitter Box Dimensions	5.5" x 7.5" x 7.5"
Receiving Box Weight	6.2 lbs
Receiving Box Dimensions	12" x 5.5" x 13"
Battery Life	Approximately 5 hours
Alignment Time	~4-5 seconds
Receiving Distance	> 50 yards

# Prototype Cost

Part	Quantity	Prototype Cost	Production cost
Power Supplies	3	\$30	\$10
Photodiodes	3	\$30	\$21
Raspberry Pi	2	\$70	\$40
Receiving Box	1	\$25	\$5
PCB	3	\$22.95	\$5
Laser	1	\$21	\$10
Gyroscope	1	\$22	\$10
Total		\$220.95	\$101

# Where will this be used

- Works best on flat turf fields
  - Professional and College stadiums
  - High-end high school fields
- Not Recommended for youth leagues
  - Inconsistencies in the grass or field layout can cause issues





# Uses Beyond Football

- House/Building Surveillance Systems
  - Notify owner when someone entered property and take picture of them
- Traffic
  - How many cars on a road
  - Toll Collection

# Automation & Operating the System

- Chain crew is still needed to operate this system
  - They will require training on how to use it
- Allows chain crew to do their job faster and display more information
  - No jobs will be lost because of this

# FPR Deliverables

- New Housing Units for Transmitter and Receiver ✓
  - Padded, Durable, Visually Appealing
- Improved Materials for Light Shield ✓
  - Matte color to avoid unwanted reflection
  - Filter in-front that will allow laser but restrict ambient light
- Improved accuracy on angle detector ✓
- Testing and Data Collection ✓

# Team Contributions

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- Josh G
  - Software
- Josh S
  - Box Designs
- Sam
  - Transmitter Design
- Tim
  - PCB and Receiving Box

Thank You

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Questions and Demo